

# Almost Security of Cryptographic Boolean Functions

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## Abstract

The propagation criteria,  $PC(\ell)$  of order  $k$ , is one of the most general cryptographic criteria of secure Boolean functions  $f$ . In this paper, we formalize its  $\varepsilon$ -almost version. The new definition requires that  $f(X) + f(X + \Delta)$  is *almost* uniformly distributed while in the original definition, it must be *strictly* uniformly distributed. Better parameters are then obtained than the strict  $PC(\ell)$  of order  $k$  functions. To construct  $\varepsilon$ -almost  $PC(\ell)$  of order  $k$  functions, we introduce a notion of *domain distance*.

**(Keywords)** Boolean functions,  $PC(\ell)$  of order  $k$ ,  $\varepsilon$ -almost version

## 1 Introduction

### 1.1 Overview

Several criterion of Boolean functions  $f$  have been developed to examine their cryptographic properties. However, the properties have shown to be contradictory in the sense that strict fulfillment in one criterion leads to less optimal fulfillment or complete failure with respect to another criterion. Previously Kurosawa, Johansson and Stinson introduced the notion

of  $\varepsilon$ -almost  $k$ -resilience [9], which relaxes, in a controlled manner, the strict requirement of  $k$ -resilience.

The goal of this paper is to extend this approach to the propagation criterion,  $PC(\ell)$  of order  $k$ . That is, we formalize an  $\varepsilon$ -almost version of  $PC(\ell)$  of order  $k$ . The new definition requires that  $f(X) + f(X + \Delta)$  is *almost* uniformly distributed while in the original definition, it must be *strictly* uniformly distributed. Better parameters are then obtained than the strict  $PC(\ell)$  of order  $k$  functions. To construct  $\varepsilon$ -almost  $PC(\ell)$  of order  $k$  functions, we introduce a notion of *domain distance*.

## 1.2 $PC(\ell)$ of order $k$ and Its almost version

$PC(\ell)$  of order  $k$  [19, 20] is one of the most general criteria among many cryptographic criteria which have been studied in order to design secure block ciphers.

A Boolean function  $f(X)$  is said to satisfy  $PC(\ell)$  if the output difference  $f(X) + f(X + \Delta)$  is uniformly distributed for any input difference  $\Delta$  with  $1 \leq wt(\Delta) \leq \ell$ , where  $wt(\Delta)$  denotes the Hamming weight of  $\Delta$ . Further suppose that  $f(X)$  satisfies  $PC(\ell)$  even if any  $k$  bits of  $X = (x_1, \dots, x_n)$  are fixed into any constants. Then we say that  $f(X)$  satisfies  $PC(\ell)$  of order  $k$ .

The famous strict avalanche criterion (SAC), which was introduced as a criterion of the security of S-boxes [21], is equivalent to  $PC(1)$ .  $SAC(k)$  is equivalent to  $PC(1)$  of order  $k$ . Also,  $f(X)$  is a bent function [11, Chapter 14] if and only if  $f(X)$  satisfies  $PC(n)$  [19], where a bent function has the largest distance from the set of affine (linear) functions. (Hence it is directly related to the linear attack.)  $PC(\ell)$  of order  $k$  in general is directly related to the security against differential attacks.

Kurosawa et al. gave a general method to design  $PC(\ell)$  of order  $k$  functions by using linear codes [10]. Carlet extended it to nonlinear codes [4].

Boolean functions, however, do not need to satisfy the strict definitions of cryptographic criteria in general. These definitions are sometimes stronger than what we want and may introduce other vulnerabilities. For example, cryptographic Boolean functions need to be balanced, but bent functions are never balanced. Therefore it would be good if by relaxing the conditions, better parameters with respect to all known attacks could be obtained.

From this point of view, this paper introduces a notion of  $\varepsilon$ -almost  $PC(\ell)$  of order  $k$ . It requires that  $f(X) + f(X + \Delta)$  is *almost* uniformly distributed while in the original definition, it must be *strictly* uniformly distributed. We

then show that indeed better parameters are obtained than the strict  $PC(\ell)$  of order  $k$  functions.

We present a design method of  $\varepsilon$ -almost  $PC(\ell)$  of order  $k$  functions using linear codes and an  $\varepsilon$ -biased sample spaces [13] which satisfy some property. To achieve our goal, we introduce a new notion of *domain distance*. Our construction offers smaller input length  $n$  than the strict  $PC(\ell)$  of order  $k$  functions for the same  $(l, k)$ . (The input size  $n$  of S-boxes can be smaller for the security level  $(l, k)$ .) In other words, we can obtain larger  $(l, k)$  for the same input length  $n$ . (Higher security level  $(l, k)$  can be obtained for the same input size  $n$  of S-boxes.)

We also show that our  $\varepsilon$ -almost  $PC(\ell)$  of order  $k$  functions have large nonlinearity, where the nonlinearity  $N(f)$  of a Boolean function  $f$  is defined by a distance between  $f$  and the set of affine functions.  $N(f)$  must be large to avoid linear attack.

We finally generalize our result to multiple output bit Boolean functions.

**Remark 1.1** We compare our construction of  $\varepsilon$ -almost  $PC(\ell)$  of order  $k$  with the strict  $PC(\ell)$  of order  $k$  functions using linear codes [10] because it is the best known construction.

It will be a further work to show that for any strict  $PC(\ell)$  of order  $k$  function, there exists a better  $\varepsilon$ -almost  $PC(\ell)$  of order  $k$  function.

### 1.3 Related work

Suppose that  $\phi(x_1, \dots, x_n) = (y_1, \dots, y_m)$  is uniformly distributed even if any  $k$  bits of  $(x_1, \dots, x_n)$  are fixed into any constant. We then say that  $\phi$  is an  $(n, m, k)$ -resilient function. This notion has been studied by several researchers from a view point of key renewal [6, 2, 8, 17, 3, 18]. Especially, a notion of  $\varepsilon$ -almost  $k$ -resilient functions was introduced in [9]. The authors presented its construction and showed that better parameters are obtained than the strict  $k$ -resilient functions. Dodis et al. improved it by showing a probabilistic construction [7].

Our work can be considered as an extension of [9]. Indeed, it is shown that an  $\varepsilon$ -almost  $PC(\ell)$  of order  $k$  function is obtained from a linear code and an  $\varepsilon$ -almost  $k$ -resilient function with a special property. The special property is characterized by our new notion of *domain distance*. We then present how to construct such  $\varepsilon$ -almost  $k$ -resilient functions by extending the technique of [9].

## 1.4 Organization

This paper is organized as follows. Sec.2 is for preliminaries. In Sec.3, we review almost resilient functions. Sec.4 formalizes a notion of  $\varepsilon$ -almost  $PC(\ell)$  of order  $k$  functions and shows our basic theorem. Our construction is presented in Sec.5. Sec.6 shows a comparison with our construction with the strict  $PC(\ell)$  of order  $k$  functions. In Sec.7, we study the nonlinearity of our construction. Sec.8 shows a generalization to multiple output bits. In Sec.9, we discuss on  $t$ -systematic almost  $k$ -wise independent sample spaces.

## 2 Preliminaries

We use  $f$  to denote a Boolean function  $\{0, 1\}^n \rightarrow \{0, 1\}$ , and  $\phi$  to denote a function  $\{0, 1\}^n \rightarrow \{0, 1\}^m$ , where  $m \leq n$ . We use  $X$  to denote  $(x_1, \dots, x_n)$ , where  $x_i$  is a binary variable.

We denote by  $wt(\Delta)$  the Hamming weight of a binary vector  $\Delta$ . Let  $\cdot$  denote the inner product of two binary vectors over  $GF(2)$ . For a set  $A$ ,  $|A|$  denotes the cardinality of  $A$ .

Let a linear  $[N, m, d]$ -code denote a binary linear code  $C$  of length  $N$ , dimension  $m$  and the minimum Hamming distance at least  $d$ . The dual code  $C^\perp$  of a linear code  $C$  is defined as  $C^\perp \triangleq \{u \mid u \cdot v = 0 \text{ for all } v \in C\}$ . The dual minimum Hamming distance  $d^\perp$  of  $C$  is defined as the minimum Hamming distance of  $C^\perp$ .

### 2.1 Resilient Functions

**Definition 2.1** We say that  $\phi : \{0, 1\}^n \rightarrow \{0, 1\}^m$  is an  $(n, m, k)$ -resilient function if  $\phi(x_1, \dots, x_n)$  is uniformly distributed even if any  $k$  variables  $x_{i_1}, \dots, x_{i_k}$  are fixed into any constants. That is,

$$\Pr[\phi(x_1, \dots, x_n) = (y_1, \dots, y_m) \mid x_{i_1}x_{i_2} \cdots x_{i_k} = \alpha] = 2^{-m}$$

for any  $k$  positions  $i_1 < \dots < i_k$ , for any  $k$ -bit string  $\alpha \in \{0, 1\}^k$  and for any fixed  $(y_1, \dots, y_m) \in \{0, 1\}^m$ , where the values  $x_j$  ( $j \notin \{i_1, \dots, i_k\}$ ) are chosen independently at random.

Chor et al. showed that an  $(n, m, k)$ -resilient function can be obtained from a linear  $[n, m, k + 1]$ -code [6].

**Proposition 2.1** Let  $G$  be a generator matrix of a linear  $[n, m, k + 1]$ -code  $C$ . Then  $\phi(X) = G \cdot X$  is an  $(n, m, k)$ -resilient function.

(Proof) Let  $\phi(X) = (y_1, \dots, y_m)$ . Then each  $y_i$  is a linear function of  $X = (x_1, \dots, x_n)$ . Further, each linear function has  $k + 1$  or more nonzero coefficients.

Now it is known that  $\phi(X) = (y_1, \dots, y_m)$  is an  $(n, m, k)$ -resilient function if and only if

$$a_1 y_1 + \dots + a_m y_m \tag{1}$$

is an  $(n, 1, k)$ -resilient function for any  $(a_1, \dots, a_m) \neq (0, \dots, 0)$ . (See [6].) In our case, expression (1) becomes as follows.

$$(a_1, \dots, a_m) \cdot GX = (b_1, \dots, b_n) \cdot X,$$

where  $(b_1, \dots, b_n) = (a_1, \dots, a_m) \cdot G$ . Note that  $wt(b_1, \dots, b_n) \geq k + 1$  because  $(b_1, \dots, b_n)$  is a nonzero codeword of  $C$ . Then it is easy to see that  $(b_1, \dots, b_n) \cdot X$  is  $k$ -resilient.

Q.E.D.

We say that  $f : \{0, 1\}^n \rightarrow \{0, 1\}$  is  $k$ -resilient if  $f$  is an  $(n, 1, k)$ -resilient function.

## 2.2 $PC(\ell)$ of order $k$

Define the derivative of  $f : \{0, 1\}^n \rightarrow \{0, 1\}$  by

$$D_\Delta f = F(X) + f(X + \Delta)$$

for  $\Delta \in \{0, 1\}^n$ .

**Definition 2.2** [19, 20] *We say that a Boolean function  $f : \{0, 1\}^n \rightarrow \{0, 1\}$  satisfies  $PC(\ell)$  of order  $k$  if  $D_\Delta f$  is  $k$ -resilient for any  $\Delta \in \{0, 1\}^n$  with  $1 \leq wt(\Delta) \leq \ell$ . (We also say that  $f$  is a  $PC(\ell)$  of order  $k$  function.)*

Kurosawa et al. gave a general method to design  $PC(\ell)$  of order  $k$  functions by using two linear codes [10].

**Proposition 2.2** *Suppose that there exist*

1. *a linear  $[n_1, m, k + 1]$ -code  $C_1$  with the dual minimum Hamming distance at least  $\ell + 1$  and*
2. *a linear  $[n_2, m, k + 1]$ -code  $C_2$  with the dual minimum Hamming distance at least  $\ell + 1$ .*

*Then there exists a  $PC(\ell)$  of order  $k$  function  $f : \{0, 1\}^n \rightarrow \{0, 1\}$  such that  $n = n_1 + n_2$ .*

### 3 Almost Resilient Functions

#### 3.1 Almost $k$ -Wise Independent Sample Space

Let  $\varepsilon$  be a constant such that  $0 \leq \varepsilon \leq 1$ . An  $\varepsilon$ -biased sample space is a subset  $S_n \subseteq \{0,1\}^n$  which looks random. To formalize this notion, we consider that  $S_n$  is an  $|S_n| \times n$  binary matrix and each row is randomly chosen.

**Definition 3.1**  $S_n$  is  $\varepsilon$ -biased if

$$\left| \Pr_{X \in S_n} (X \cdot \alpha = 0) - \Pr_{X \in S_n} (X \cdot \alpha = 1) \right| \leq \varepsilon$$

for any  $\alpha \in \{0,1\}^n \setminus \{0^n\}$ . We also say that  $S_n$  is an  $\varepsilon$ -biased sample space.

An almost  $k$ -wise independent sample space is a subset  $S_N \subseteq \{0,1\}^N$  such that any  $k$  out of  $N$  bits look random. To formalize this notion, we consider that  $S_N$  is an  $|S_N| \times N$  binary matrix and each row is randomly chosen.

**Definition 3.2** (almost  $k$ -wise independence). Suppose that  $X = x_1 \cdots x_N$  is chosen randomly from  $S_N$ . Then we say that  $S_N$  is  $(\varepsilon, k)$ -independent if for any  $k$  positions  $i_1 < i_2 < \cdots < i_k$  and any  $k$ -bit string  $\alpha$ , we have

$$|\Pr[x_{i_1} x_{i_2} \cdots x_{i_k} = \alpha] - 2^{-k}| \leq \varepsilon.$$

(We also say that  $S_N$  is an almost  $k$ -wise independent sample space.)

It is known that a large almost  $k$ -wise independent sample space  $S_N$  can be obtained from a small  $\varepsilon$ -biased sample space  $S_n$ , where  $N > n$ .

**Proposition 3.1** [13] Suppose that  $S_n$  is  $\varepsilon$ -biased. Let  $H$  be a parity check matrix of a  $[N, N - n, k + 1]$ -linear code  $C$ . Define

$$S_N \triangleq S_n \cdot H \tag{2}$$

Then  $S_N$  is  $(\tilde{\varepsilon}, k)$ -independent, where

$$\tilde{\varepsilon} = \left(1 - \frac{1}{2^k}\right) \cdot \varepsilon$$

### 3.2 Almost Resilient Functions

Kurosawa, Johansson and Stinson introduced a notion of  $\varepsilon$ -almost  $k$ -resilient functions [9]. It is an  $\varepsilon$ -almost version of  $(n, m, k)$ -resilient functions.

**Definition 3.3** [9] We say that  $\phi : \{0, 1\}^n \rightarrow \{0, 1\}^m$  is an  $\varepsilon$ -almost  $(n, m, k)$ -resilient function if

$$|\Pr[\phi(x_1, \dots, x_n) = (y_1, \dots, y_m) \mid x_{i_1}x_{i_2} \cdots x_{i_k} = \alpha] - 2^{-m}| \leq \varepsilon$$

for any  $k$  positions  $i_1 < \cdots < i_k$ , for any  $k$ -bit string  $\alpha \in \{0, 1\}^k$  and for any fixed  $(y_1, \dots, y_m) \in \{0, 1\}^m$ , where the values  $x_j$  ( $j \notin \{i_1, \dots, i_k\}$ ) are chosen independently at random.

The authors presented its construction by using  $t$ -systematic  $(\varepsilon, k)$ -independent sample spaces [9].

**Definition 3.4** [9] An  $(\varepsilon, k)$ -independent sample space  $S_N$  is called  $t$ -systematic if  $|S_N| = 2^t$ , and there exist  $t$  positions  $i_1 < \cdots < i_t$  such that each  $t$ -bit string occurs in these positions for exactly one  $N$ -tuple in  $S_N$ .

$t$ -systematic  $\varepsilon$ -biased sample spaces are defined similarly.

**Proposition 3.2** [9, Theorem 4.4] *If there exists a  $t$ -systematic  $(\varepsilon, k)$ -independent sample space  $S_N$ , then there exists a balanced  $\delta$ -almost  $(N, N-t, k)$ -resilient function  $\phi$ , where  $\delta = \varepsilon/2^{N-t-k}$ .*

(Proof sketch) Without loss of generality, assume that the first  $t$  positions in  $S_N$  run through all possible  $t$ -bit strings. We construct  $2^{N-t}$  sample spaces  $E_\alpha$  indexed by  $\alpha = (\alpha_1, \dots, \alpha_{N-t}) \in \{0, 1\}^{N-t}$  by

$$E_\alpha = S_N + \underbrace{(0, 0, \dots, 0)}_t, \alpha_1, \dots, \alpha_{N-t}.$$

Finally define a function  $\phi : \{0, 1\}^N \rightarrow \{0, 1\}^{N-t}$  by the rule

$$\phi(x_1, \dots, x_N) = \alpha \text{ if and only if } (x_1, \dots, x_N) \in E_\alpha. \quad (3)$$

Then  $\phi$  is a  $\delta$ -almost  $(N, N-t, k)$ -resilient function with  $\delta = \varepsilon/2^{N-t-k}$ .

Q.E.D.

## 4 Almost $PC(\ell)$ of order $k$

In this section, we formalize a notion of  $\varepsilon$ -almost  $PC(\ell)$  of order  $k$  functions. It is an  $\varepsilon$ -almost version of  $PC(\ell)$  of order  $k$  functions.

### 4.1 Definition

**Definition 4.1** We say that  $f : \{0, 1\}^n \rightarrow \{0, 1\}$  satisfies  $\varepsilon$ -almost  $PC(\ell)$  of order  $k$  if its derivative  $D_\Delta f$  is an  $\varepsilon$ -almost  $(n, 1, k)$ -resilient function for any  $\Delta \in \{0, 1\}^n$  with  $1 \leq wt(\Delta) \leq l$ . (We also say that  $f(X)$  is an  $\varepsilon$ -almost  $PC(\ell)$  of order  $k$  function.)

The definitions of " $PC(\ell)$  of order  $k$ " and " $\varepsilon$ -almost  $PC(\ell)$  of order  $k$ " are summarized in the following table.

$f$	$PC(\ell)$ of order $k$	$\varepsilon$ -almost $PC(\ell)$ of order $k$
$D_\Delta f$	$(n, 1, k)$ -resilient function for any $\Delta$ with $1 \leq wt(\Delta) \leq l$	$\varepsilon$ -almost $(n, 1, k)$ -resilient function for any $\Delta$ with $1 \leq wt(\Delta) \leq l$

### 4.2 Basic Theorem

We show that an almost  $PC(\ell)$  of order  $k$  function is obtained from a linear code and an  $\varepsilon$ -almost  $(n, m, k)$ -resilient function which satisfies some property. We first introduce a notion of *domain distance*.

**Definition 4.2** For a function  $\phi : \{0, 1\}^n \rightarrow \{0, 1\}^m$  and for any  $\alpha \in \{0, 1\}^m$ , define

$$C_\alpha = \{X \mid \phi(X) = \alpha\}.$$

Let  $d_\alpha$  be the minimum Hamming distance of a code  $C_\alpha$ . Then we define the domain distance  $d_\phi$  of  $\phi$  by

$$d_\phi = \min_\alpha d_\alpha.$$

**Lemma 4.1** Suppose that a function  $\phi : \{0, 1\}^n \rightarrow \{0, 1\}^m$  has the domain distance  $d_\phi$ . Then

$$\phi(\beta) \neq \phi(\beta + \Omega)$$

for any  $\beta \in \{0, 1\}^n$  if  $1 \leq wt(\Omega) \leq d_\phi - 1$ .

(Proof) Suppose that

$$\alpha = \phi(\beta) = \phi(\beta + \Omega)$$

for some  $\alpha \in \{0, 1\}^m$ ,  $\beta \in \{0, 1\}^n$  and  $\Omega \in \{0, 1\}^n$  with  $1 \leq wt(\Omega) \leq d_\phi - 1$ . Then  $d_\alpha < d_\phi$ , where  $d_\alpha$  is the minimum Hamming distance of  $C_\alpha$ . This is a contradiction.

Q.E.D.

We next prove the following lemma.

**Lemma 4.2** *Let  $\phi : \{0, 1\}^n \rightarrow \{0, 1\}^m$  be an  $\varepsilon$ -almost  $(n, m, k)$ -resilient function with  $2^{m-1}\varepsilon \leq 1$ . Then  $\phi(X) \cdot \Delta$  is a  $(2^{m-1}\varepsilon)$ -almost  $(n, 1, k)$ -resilient function for any  $\Delta \neq (0, \dots, 0)$ , where  $X = (x_1, \dots, x_n)$ .*

(Proof) For any  $\Delta \neq (0, \dots, 0)$ , let

$$A_0 = \{Y \mid Y \cdot \Delta = 0\}, \quad A_1 = \{Y \mid Y \cdot \Delta = 1\}.$$

Then  $|A_0| = |A_1| = 2^{m-1}$ . Therefore,

$$\Pr(\phi(X) \cdot \Delta = 0) = \sum_{\alpha \in A_0} \Pr(\phi(X) = \alpha) \geq \sum_{\alpha \in A_0} (2^{-m} - \varepsilon) = 1/2 - 2^{m-1}\varepsilon.$$

Similarly we have

$$\Pr(\phi(X) \cdot \Delta = 0) \leq 1/2 + 2^{m-1}\varepsilon.$$

Hence

$$|\Pr(\phi(X) \cdot \Delta = 0) - 1/2| \leq 2^{m-1}\varepsilon.$$

Similarly,

$$|\Pr(\phi(X) \cdot \Delta = 1) - 1/2| \leq 2^{m-1}\varepsilon.$$

Q.E.D.

Then our basic theorem is stated as follows.

**Theorem 4.1** *Suppose that there exist*

1. *a linear  $[n_1, m, k + 1]$ -code  $C_1$  with the dual minimum Hamming distance at least  $\ell + 1$  and*
2. *an  $\varepsilon$ -almost  $(n'_2, m, k)$ -resilient function  $\phi$  with the domain distance  $d_\phi \geq \ell + 1$ .*

Then there exists a  $\delta$ -almost  $PC(\ell)$  of order  $k$  function  $f : \{0, 1\}^n \rightarrow \{0, 1\}$  such that  $\delta = 2^{m-1}\varepsilon$  and  $n = n_1 + n'_2$ .

(Proof) Let  $G_1$  be a generator matrix of  $C_1$ . Define a Boolean function  $f : \{0, 1\}^n \rightarrow \{0, 1\}$  with  $n = n_1 + n'_2$  as follows. For  $X = (x_1, \dots, x_{n_1})$  and  $Y = (y_1, \dots, y_{n'_2})$ , let

$$f(X, Y) = \phi(Y) \cdot G_1 X + \pi(Y), \quad (4)$$

where  $\pi : \{0, 1\}^{n'_2} \rightarrow \{0, 1\}$  is any Boolean function. We show that  $f(X, Y)$  satisfies  $(2^{m-1}\varepsilon)$ -almost  $PC(\ell)$  of order  $k$ . Define the derivative of  $f$  by

$$D_{(\Delta, \Omega)} f(X, Y) = f(X, Y) + f(X + \Delta, Y + \Omega).$$

Then

$$\begin{aligned} D_{(\Delta, \Omega)} f(X, Y) &= (\phi(Y) + \phi(Y + \Omega)) \cdot G_1 X + \phi(Y + \Omega) \cdot G_1 \Delta \\ &\quad + \pi(Y) + \pi(Y + \Omega) \end{aligned}$$

**Case 1.** Suppose that  $\Omega = 0$  and  $1 \leq wt(\Delta) \leq l$ . In this case,

$$D_{(\Delta, \Omega)} f(X, Y) = \phi(Y) \cdot G_1 \Delta.$$

Then  $G_1 \Delta \neq \mathcal{O}$  because  $\Delta$  is not a codeword of  $C_1^\perp$ . Hence  $D_{(\Delta, \Omega)} f(X, Y)$  is  $(2^{m-1}\varepsilon)$ -almost  $k$ -resilient from Lemma 4.2.

**Case 2.** Suppose that  $\Omega \neq 0$  and  $1 \leq wt(\Delta) + wt(\Omega) \leq l$ . Then for any  $\beta$ ,

$$D_{(\Delta, \Omega)} f(X, \beta) = (\phi(\beta) + \phi(\beta + \Omega)) \cdot G_1 X + \gamma,$$

where  $\gamma = \phi(\beta + \Omega) \cdot G_1 \Delta + \pi(\beta) + \pi(\beta + \Omega)$  is a constant. Now

$$\phi(\beta) \neq \phi(\beta + \Omega)$$

because  $d_\phi \geq \ell + 1$ . Therefore,  $D_{(\Delta, \Omega)} f(X, \beta)$  is  $k$ -resilient from the proof of Proposition 2.1.

This means that  $D_{(\Delta, \Omega)} f(X, Y)$  is  $k$ -resilient.

Consequently,  $f(X, Y)$  satisfies  $2^{m-1}\varepsilon$ -almost  $PC(\ell)$  of order  $k$ .

Q.E.D.

### 4.3 Discussion

Eq.(4) gives a general formula of our  $\delta$ -almost  $PC(\ell)$  of order  $k$  function. Note that Proposition 2.2 can be seen as a corollary of Theorem 4.1.

Indeed, in eq.(4), let  $\phi(Y) = G_2Y$ , where  $G_2$  is a generator matrix of a linear  $[n_2, m, k + 1]$ -code  $C_2$ . Then  $\phi(Y)$  is a  $(n_2, m, k)$ -resilient function from Proposition 2.1. In this case, it is easy to see that the  $d_\phi$  is equal to the dual minimum Hamming distance of  $C_2$ .

The relationship between Proposition 2.2 and Theorem 4.1 is summarized in the following table.

	Proposition 2.2	Theorem 4.1
$\phi(Y)$	$G_2Y$ ( $[n_2, m, k + 1]$ -code)	$\varepsilon$ -almost $(n'_2, m, k)$ -resilient function
$d_\phi$	dual minimum Hamming distance of $C_2$	domain distance of $\phi$
$\varepsilon$	0	$\varepsilon > 0$
$\delta$	0	$2^{m-1}\varepsilon$
$n$	$n_1 + n_2$	$n_1 + n'_2$

Now suppose that there exists a linear  $[n_2, m, k + 1]$ -code with the dual minimum Hamming distance at least  $\ell + 1$ . In what follows, we show that there exists an  $\varepsilon$ -almost  $(n'_2, m, k)$ -resilient function with the domain distance at least  $\ell + 1$  such that  $n'_2 < n_2$ .

This means that we can obtain smaller input length  $n$  for the same  $(l, k)$ . In other words, we can obtain larger  $(l, k)$  for the same  $n$ .

## 5 Construction

### 5.1 Outline

From the proof of Theorem 4.1, we can construct a  $(2^{m-1}\varepsilon)$ -almost  $PC(\ell)$  of order  $k$  function  $f$  by using a linear  $[n_1, m, k + 1]$ -code  $C_1$  with the dual minimum Hamming distance at least  $\ell + 1$  and an  $\varepsilon$ -almost  $(n_2, m, k)$ -resilient function  $\phi$  with the domain distance  $d_\phi \geq \ell + 1$ .

In this section, we show how to achieve the second condition, i.e. how to construct an  $\varepsilon$ -almost  $(n, m, k)$ -resilient function with the domain distance at least  $\ell + 1$ .

We define the domain distance of an  $(\varepsilon, k)$ -independent sample space  $S_N$  as follows.

**Definition 5.1** For an  $(\varepsilon, k)$ -independent sample space  $S_N$ , let  $C(S_N)$  be a nonlinear code such that each row of  $S_N$  is a codeword. Then we say that  $S_N$  has the domain distance  $d$ , where  $d$  is the minimum Hamming distance of  $C(S_N)$ .

It is easy to see that the domain distance  $d_\phi$  of  $\phi$  defined by eq.(3) is equal to the minimum Hamming distance of  $C(S_N)$ . Therefore, it is reasonable to define the domain distance of an  $(\varepsilon, k)$ -independent sample space  $S_N$  as above.

Now our construction is outlined as follows.

**Step 1.** We first show that the second condition of Theorem 4.1 is satisfied if there exists a  $t$ -systematic  $(\varepsilon, k)$ -independent sample space  $S_N$  whose domain distance is at least  $\ell + 1$ .

**Step 2.** We next show that such  $S_N$  is obtained from a  $t$ -systematic  $\varepsilon$ -biased sample space  $S_n$  and a linear  $[N, N - n, k + 1]$ -code with the dual minimum Hamming distance at least  $\ell + 1$ .

**Step 3.** We finally show how to construct such  $S_n$  by using Weil-Carlitz-Uchiyama bound. (The same technique was used in [9] to construct a  $t$ -systematic  $(\varepsilon, k)$ -independent sample space  $S_N$  directly.)

## 5.2 Step 1 $\sim$ Step 3

We show Step 1  $\sim$  Step 3 of the previous subsection.

**Theorem 5.1** Suppose that there exists a  $t$ -systematic  $(\varepsilon, k)$ -independent sample space  $S_N$  with the domain distance at least  $\ell + 1$ . Then there exists a balanced  $\delta$ -almost  $(N, N - t, k)$ -resilient function  $\phi$  with the domain distance  $d_\phi$  at least  $\ell + 1$ , where  $\delta = \varepsilon/2^{N-t-k}$ .

(Proof) Construct  $\phi$  from  $S_N$  as shown in the proof of Proposition 3.2. Then the  $\phi$  is a balanced  $\delta$ -almost  $(N, N - t, k)$ -resilient function.

Next suppose that  $d_\phi \leq l$ . That is,  $\phi(\beta) = \phi(\beta + \Omega) = \alpha$  for some  $\alpha, \beta$  and  $\Omega$  such that  $1 \leq wt(\Omega) \leq l$ . Then we see that

$$\beta + (0, \dots, 0, \alpha) \in S_N \text{ and } \beta + \Omega + (0, \dots, 0, \alpha) \in S_N.$$

This means that there are two codewords with the distance  $l$  or less in  $S_N$ . However, this is a contradiction because  $S_N$  has the domain distance at least  $\ell + 1$ .

Q.E.D.

**Theorem 5.2** *Suppose that there exists a  $t$ -systematic  $\varepsilon$ -biased sample space  $S_n$  and a linear  $[N, N - n, k + 1]$ -code  $C$  with the dual minimum Hamming distance at least  $\ell + 1$ . Then there exists a  $t$ -systematic  $(\tilde{\varepsilon}, k)$ -independent sample space  $S_N$  with the domain distance at least  $\ell + 1$ , where*

$$\tilde{\varepsilon} = \left(1 - \frac{1}{2^k}\right) \cdot \varepsilon.$$

(Proof) Let  $H = (I_n, \tilde{H})$  be a parity check matrix of  $C$ , where  $I_n$  is the  $n \times n$  identity matrix. Let

$$S_N = S_n \cdot H. \quad (5)$$

Then  $S_N$  is  $(\tilde{\varepsilon}, k)$ -independent from Proposition 3.1, where

$$\tilde{\varepsilon} = \left(1 - \frac{1}{2^k}\right) \cdot \varepsilon$$

Next it is easy to see that  $S_N$  is  $t$ -systematic if  $S_n$  is  $t$ -systematic.

Finally, we show that  $S_N$  has the domain distance at least  $\ell + 1$ . From eq.(5), we see that  $S_N$  is a subset of all codewords of  $C^\perp$ . Therefore  $S_N$  has the domain distance at least  $\ell + 1$  because  $C$  has the dual distance at least  $\ell + 1$ .

Q.E.D.

We next show how to construct a  $t$ -systematic  $\varepsilon$ -biased sample space  $S_n$  by using Weil-Carlitz-Uchiyama bound. For  $x \in GF(2^t)$ , let

$$\text{Tr}(x) \triangleq x + x^2 + x^{2^2} + \cdots + x^{2^{t-1}}.$$

It is well-known that  $\text{Tr}(x) = 0$  or  $1$  and  $\text{Tr}(x_1 + x_2) = \text{Tr}(x_1) + \text{Tr}(x_2)$ .

**Proposition 5.1** (Weil-Carlitz-Uchiyama Bound) [11, Chapter 9, Theorem 19] *Let  $f(x) = \sum_{i=1}^D f_i x^i \in GF(2^t)[x]$  be a polynomial such that  $f(x) \neq g(x)^2 - g(x) + \theta$  for any polynomial  $g(x) \in GF(2^t)[x]$  and for any constant  $\theta \in F_{2^t}$ . Then*

$$\left| \sum_{\alpha \in GF(2^t)} (-1)^{\text{Tr}(f(\alpha))} \right| \leq (D - 1)\sqrt{2^t}.$$

**Remark 5.1** *It is easy to see that if  $f(x)$  is an odd degree polynomial, then  $f(x) \neq g(x)^2 - g(x) + \theta$  for any  $g(x)$  and any  $\theta$ .*

Now for two positive integers  $t$  and  $D'$ , let  $n = tD'$  and  $D = 2D' - 1$ . Let  $g$  be a primitive element of  $GF(2^t)$  and  $x_1, x_2, \dots, x_{2^t}$  be the elements of  $GF(2^t)$ . For each  $x_i \in GF(2^t)$ , let  $X_i$  be a string of length  $n = tD'$  such that

$$X_i \triangleq (Z_{i,1}, Z_{i,2}, \dots, Z_{i,D'}),$$

where

$$Z_{i,j} \triangleq (\text{Tr}(x_i^{2^{j-1}}), \text{Tr}(gx_i^{2^{j-1}}), \dots, \text{Tr}(g^{t-1}x_i^{2^{j-1}})).$$

The proposed  $\varepsilon$ -biased sample space is defined as

$$S_n = \begin{pmatrix} X_1 \\ \vdots \\ X_{2^t} \end{pmatrix} \quad (6)$$

**Theorem 5.3** *The above  $S_n \subseteq \{0, 1\}^n$  is a  $t$ -systematic  $\varepsilon$ -biased sample space such that  $n = tD'$ ,  $|S_n| = 2^t$  and*

$$\varepsilon = \frac{2(D' - 1)}{\sqrt{2^t}}.$$

(Proof) First it is a well known fact [9, page 245] that

$$Y_x = (\text{Tr}(x), \text{Tr}(gx), \dots, \text{Tr}(g^{t-1}x))$$

runs through  $\{0, 1\}^t$  when  $x$  runs through  $GF(2^t)$ . Hence  $S_n$  is  $t$ -systematic.

Next consider  $\alpha \in \{0, 1\}^n \setminus \{0^n\}$ . Let  $\alpha = (\Lambda_1, \Lambda_2, \dots, \Lambda_{D'})$ , where

$$\Lambda_j = (\alpha_{0,2j-1}, \alpha_{1,2j-1}, \dots, \alpha_{t-1,2j-1}).$$

Then since  $\alpha_{i,j}$  is binary, we have that

$$\begin{aligned} X_i \cdot \alpha &= \sum_{j=1}^{D'} (\alpha_{0,2j-1} \text{Tr}(x_i^{2^{j-1}}) + \dots + \alpha_{t-1,2j-1} \text{Tr}(g^{t-1}x_i^{2^{j-1}})) \\ &= \sum_{j=1}^{D'} \text{Tr}(\alpha_{0,2j-1} + \alpha_{1,2j-1}g + \dots + \alpha_{t-1,2j-1}g^{t-1})x_i^{2^{j-1}} \\ &= \text{Tr}(a_1x_j + a_3x_i^3 + \dots + a_Dx_i^D), \end{aligned} \quad (7)$$

where

$$a_j \triangleq \alpha_{0,j} + \alpha_{1,j}g + \dots + \alpha_{t-1,j}g^{t-1}$$

Since  $g$  is a primitive element,  $a_j = 0$  if and only if  $(\alpha_{0,j}, \alpha_{1,j}, \dots, \alpha_{t-1,j}) = (0, \dots, 0)$ . This implies that  $(a_1, \dots, a_D) \neq (0, \dots, 0)$  because  $\alpha \neq 0$ .

Now define

$$f_i(x) \triangleq a_1 x_i + a_3 x_i^3 + \dots + a_D x_i^D$$

Let

$$A_0 \triangleq \{x_i | \text{Tr}(f(x_i)) = 0\}, \quad A_1 \triangleq \{x_i | \text{Tr}(f(x_i)) = 1\}.$$

Then we see that

$$\begin{aligned} |\Pr(X \cdot \alpha = 0) - \Pr(X \cdot \alpha = 1)| &= \left| \frac{|A_0|}{2^t} - \frac{|A_1|}{2^t} \right| \\ &= \frac{1}{2^t} \left| \sum_{x_i \in GF(2^t)} (-1)^{\text{Tr}(f(x_i))} \right|. \end{aligned}$$

Finally from Weil-Carlitz-Uchiyama bound (see Remark 5.1, too), we have

$$|\Pr(X \cdot \alpha = 0) - \Pr(X \cdot \alpha = 1)| \leq \frac{(D-1)\sqrt{2^t}}{2^t} = \frac{D-1}{\sqrt{2^t}}.$$

Hence

$$\varepsilon = \frac{D-1}{\sqrt{2^t}} = \frac{2(D'-1)}{2^{t/2}}.$$

Q.E.D.

### 5.3 Final Construction

**Corollary 5.1** *Suppose there exists a linear  $[N, N - tD', k + 1]$ -code  $C$  with the dual distance at least  $\ell + 1$ . Then there exists a balanced  $\delta$ -almost  $(N, N - t, k)$ -resilient function with the domain distance at least  $\ell + 1$  such that*

$$\delta = \left(1 - \frac{1}{2^k}\right) \frac{2(D'-1)\sqrt{2^t}}{2^{N-k}}.$$

(Proof) From Theorem 5.1, 5.2 and 5.3. More precisely, it is illustrated as follows.

$t$ -systematic  $\varepsilon$ -biased sample space  $S_n$  such that  
 $n = tD', |S_n| = 2^t$  and  $\varepsilon = 2(D'-1)/\sqrt{2^t}$  (Theorem 5.3)

+

Linear  $[N, N - tD', k + 1]$ -code  $C$  with the dual minimum Hamming distance at least  $\ell + 1$ .

↓ Theorem 5.2

$t$ -systematic  $(\tilde{\varepsilon}, k)$ -independent sample space  $S_N$  with the domain distance at least  $\ell + 1$ , where

$$\tilde{\varepsilon} = \left(1 - \frac{1}{2^k}\right) \cdot \varepsilon.$$

↓ Theorem 5.1

Balanced  $\delta$ -almost  $(N, N - t, k)$ -resilient function  $\phi$  with the domain distance  $d_\phi$  at least  $\ell + 1$ , where

$$\delta = \tilde{\varepsilon}/2^{N-t-k} = \left(1 - \frac{1}{2^k}\right) \frac{2(D' - 1)\sqrt{2^t}}{2^{N-k}}.$$

Q.E.D.

We finally obtain the following corollary.

**Corollary 5.2** *Suppose that there exist*

1. *a linear  $[n_1, m, k + 1]$ -code  $C_1$  with the dual minimum Hamming distance at least  $\ell + 1$  and*
2. *a linear  $[n'_2, m - (D' - 1)t, k + 1]$ -code  $C'_2$  with the dual minimum Hamming distance at least  $\ell + 1$*

*Then there exists a  $\tilde{\delta}$ -almost PC( $\ell$ ) of order  $k$  function  $f : \{0, 1\}^{n'} \rightarrow \{0, 1\}$  such that  $n' = n_1 + n'_2$  and*

$$\tilde{\delta} = \left(1 - \frac{1}{2^k}\right) \frac{2(D' - 1)}{2^{(t/2)+1-k}}.$$

(Proof) From Theorem 4.1 and Corollary 5.1. It is illustrated as follows.

Linear  $[N, N - tD', k + 1]$ -code  $C_2$  with the dual distance at least  $\ell + 1$ .

↓ (Corollary 5.1)

Balanced  $\delta$ -almost  $(N, N - t, k)$ -resilient function  
with the domain distance at least  $\ell + 1$ , where

$$\delta = \left(1 - \frac{1}{2^k}\right) \frac{2(D' - 1)\sqrt{2^t}}{2^{N-k}}.$$

+

Linear  $[n_1, N - t, k + 1]$ -code  $C_1$  with  
the dual minimum Hamming distance at least  $\ell + 1$ .

↓ (Theorem 4.1)

$\tilde{\delta}$ -almost  $PC(\ell)$  of order  $k$  function  $f : \{0, 1\}^n \rightarrow \{0, 1\}$ ,  
where  $n' = n_1 + n'_2$  and

$$\tilde{\delta} = 2^{m-1}\delta = 2^{m-1} \left(1 - \frac{1}{2^k}\right) \frac{2(D' - 1)\sqrt{2^t}}{2^{N-k}}.$$

Finally, by letting  $m = N - t$  and  $n'_2 = N$ , we obtain this corollary.

Q.E.D.

To summarize, a  $\tilde{\delta}$ -almost  $PC(\ell)$  of order  $k$  function is constructed as follows.

1. Construct a  $t$ -systematic  $\varepsilon$ -biased sample space  $S_{n_0}$  with  $n_0 = tD'$  by using Theorem 5.3, where

$$\varepsilon = \frac{2(D' - 1)}{\sqrt{2^t}}.$$

2. Let  $H$  be a parity check matrix of a linear  $[N, N - tD', k + 1]$ -code  $C'_2$  with the dual minimum Hamming distance at least  $l + 1$ . Define  $S_N = S_{n_0}H$ . Then  $S_N$  is a  $t$ -systematic  $(\tilde{\varepsilon}, k)$ -independent sample space with the domain distance at least  $l + 1$  from Theorem 5.2, where

$$\tilde{\varepsilon} = \left(1 - \frac{1}{2^k}\right) \cdot \varepsilon.$$

3. From  $S_N$ , construct a balanced  $\delta$ -almost  $(N, N - t, k)$ -resilient function  $\phi$  with the domain distance  $d_\phi$  at least  $l + 1$  by using Theorem 5.1, where

$$\delta = \tilde{\varepsilon}/2^{N-t-k} = \left(1 - \frac{1}{2^k}\right) \frac{2(D' - 1)\sqrt{2^t}}{2^{N-k}}.$$

4. Let  $G_1$  be a generator matrix of a linear  $[n_1, N - t, k + 1]$ -code  $C_1$  with the dual minimum Hamming distance at least  $l + 1$ . Define

$$f(X, Y) = \phi(Y) \cdot G_1 X + \pi(Y),$$

where  $\pi : \{0, 1\}^N \rightarrow \{0, 1\}$  is any Boolean function. Then  $f(X, Y)$  is a  $\tilde{\delta}$ -almost  $PC(\ell)$  of order  $k$  function from Corollary 5.2, where the input length is  $n = n_1 + N$  and

$$\tilde{\delta} = \left(1 - \frac{1}{2^k}\right) \frac{2(D' - 1)}{2^{(t/2)+1-k}}.$$

## 6 Comparison

Proposition 2.2 can be seen as a corollary of Corollary 5.2. Indeed, let  $D' = 1$  in Corollary 5.2. Then we obtain Proposition 2.2.

Now let's compare the parameters of  $\epsilon$ -almost  $PC(\ell)$  of order  $k$  functions (Corollary 5.2) with the strict  $PC(\ell)$  of order  $k$  functions (Proposition 2.2).

- In Proposition 2.2, the dimension of  $C_2$  is equal to  $m$ .
- In Corollary 5.2, the dimension of  $C'_2$  is equal to  $m - (D' - 1)t$ .

Therefore,  $n'_2 < n_2$  because  $m - (D' - 1)t < m$ . Hence  $n' < n$ .

This shows that our construction has a smaller input length for the same  $(l, k)$ . In other words, our construction has larger  $(l, k)$  for the same input length  $n$ . (From Corollary 5.2, we can also see that the larger  $t$  is, the smaller both  $\tilde{\delta}$  and  $m - (D' - 1)t$  are.)

As an example, first try to construct a  $PC(1)$  of order 2 function by using Proposition 2.2 from a linear  $[n_1, m = 40, k + 1 \geq 3]$  code  $C_1$  which has the dual minimum hamming distance at least 2. Suppose that  $n_2 = 41$ . Then from Proposition 2.2, we need a linear  $[41, m = 40, k + 1]$ -code  $C_2$ . However, it is clear that  $k \leq 1$  for  $n_2 = 41$  and  $m = 40$ . Hence we cannot construct a  $PC(1)$  of order 2 function for  $C_1$  and  $n_2 = 41$ .

Next consider to construct  $\tilde{\delta}$ -almost a  $PC(1)$  of order 2 function by using Corollary 5.2 for the same  $C_1$  and  $n'_2 = n_2 = 41$ . Let  $D' = 2$  and  $t = 30$  in Corollary 5.2. Then we see that a linear  $[41, 11, k + 1]$ -code  $C_2$  with the dual minimum hamming distance at least 2 is necessary.

Now as shown below, there exists a linear  $[41, 11, 3]$ -code  $C_2$  with the dual minimum hamming distance at least 2. Hence we can construct a  $\tilde{\delta}$ -almost  $PC(1)$  of order 2 function with the input length  $n = n_1 + 41$ , where

$$\tilde{\delta} = \left(1 - \frac{1}{2^k}\right) \frac{1}{2^{15-k}} = \frac{3}{4} \times \frac{1}{2^{13}}$$

We finally show that there exists a linear  $[41, 11, 3]$ -code. Consider a BCH-code  $C_1$  whose generator polynomial  $\tilde{g}(x)$  has  $g$  as a root, where  $g$  is a primitive element of  $GF(2^5)$ . Then we obtain a linear  $[31, 26, 3]$ -code [11, p. 204]. Its dual code  $C_1^\perp$  is also a cyclic code such that the generator polynomial  $\tilde{g}^\perp(x)$  has 1 as a root [16, p. 227, Eq. (2.10)]. Therefore, the parity check matrix of  $C_1^\perp$  includes a row of  $(1, \dots, 1)$ . [11, p. 203, Eq (19)]. This means that  $C_1$  has  $(1, \dots, 1)$  as a codeword.

Let the basis of  $C_1$  be  $\vec{g}_1, \dots, \vec{g}_{26}$ , where

$$\vec{g}_1 = (1, 1, \dots, 1)$$

Define

$$\begin{aligned} \vec{h}_1 &= (\vec{g}_1, 1, 1, \dots, 1), \\ \vec{h}_i &= (\vec{g}_i, 0, 0, \dots, 0), \end{aligned}$$

for  $i \geq 2$ , where  $\vec{h}_i$  is a binary vector of length 41. Let  $C$  be a linear code such that  $\vec{h}_1, \dots, \vec{h}_{11}$  are the basis of  $C$ . Then  $C$  is a linear  $[41, 11, 3]$ -code which includes  $(1, \dots, 1)$  as a codeword. It implies that the minimum Hamming distance  $d^\perp$  of the dual code  $C^\perp$  is even. That is  $d^\perp \geq 2$ .

## 7 On Other Cryptographic Criteria

To simplify the notation, let  $s = n_1$  and  $u = n'_2$  in Corollary 5.2. Then our  $\tilde{\delta}$ -almost  $PC(\ell)$  of order  $k$  function  $f : \{0, 1\}^n \rightarrow \{0, 1\}$  is written as

$$f(X, Y) = \phi(Y) \cdot G_1 X + \pi(Y) \tag{8}$$

from eq.(4), where

- $X = (x_1, \dots, x_s)$  and  $Y = (y_1, \dots, y_u)$ .
- $\phi : \{0, 1\}^u \rightarrow \{0, 1\}^m$  is an  $\varepsilon$ -almost  $(u, m, k)$ -resilient function with the domain distance  $d_\phi \geq \ell + 1$ .

- $G_1$  is a generator matrix of a linear  $[s, m, k + 1]$ -code  $C_1$  with the dual minimum Hamming distance at least  $\ell + 1$ .
- $\pi : \{0, 1\}^u \rightarrow \{0, 1\}$  is any Boolean function.

## 7.1 Balance

We say that  $f : \{0, 1\}^n \rightarrow \{0, 1\}$  is balanced if

$$|\{X \mid f(X) = 0\}| = |\{X \mid f(X) = 1\}| = 2^{n-1}.$$

In this subsection, we show that our  $f$  is balanced if  $\pi$  is chosen appropriately in eq.(8).

**Definition 7.1** For  $\phi$ , define

$$ZERO_\phi = \{Y \mid \phi(Y) = (0, \dots, 0)\}.$$

We say that  $\pi$  is balanced for  $\phi$  if

$$|\{Y \mid \pi(Y) = 0, Y \in ZERO_\phi\}| = |\{Y \mid \pi(Y) = 1, Y \in ZERO_\phi\}|. \quad (9)$$

**Theorem 7.1** Our  $f$  is balanced if  $\pi$  is balanced for  $\phi$  in (8).

(Proof) Substitute  $Y = \alpha$  into (8), where  $\alpha \in \{0, 1\}^u$  is a constant. Then we have

$$f(X, \alpha) = \phi(\alpha) \cdot G_1 X + \pi(\alpha). \quad (10)$$

(Case 1) If  $\phi(\alpha) \neq (0, \dots, 0)$ , then the right hand side of (10) is a non-constant affine function on  $X$ . In this case,  $f(X, \alpha)$  is balanced as a function on  $X$ .

(Case 2) If  $\phi(\alpha) = (0, \dots, 0)$ , then we have

$$f(X, \alpha) = \pi(\alpha).$$

In this case,  $f(X, \alpha) = 0$  for a half of  $\alpha \in ZERO_\phi$  and  $f(X, \alpha) = 1$  for the half of  $\alpha \in ZERO_\phi$  because  $\pi$  is balanced for  $\phi$ .

The above argument implies that  $f$  is balanced.

Q.E.D.

We show that it is easy to find a  $\pi$  which is balanced for  $\phi$ . A trivial way is to write down the truth table of  $\pi$ .

Another way is as follows. From the proofs of Theorem 5.1 and Proposition 3.2, we see that  $\phi(Y) = (0, \dots, 0)$  if and only if  $Y \in E_{(0, \dots, 0)} = S_N$ .

Therefore,  $ZERO_\phi = S_N$ , where  $S_N$  is a  $t$ -systematic  $(\varepsilon, k)$ -independent sample space. Assume that the first  $t$  positions in  $S_N$  run through all possible  $t$ -bit strings. Define  $\pi$  by

$$\pi(y_1, \dots, y_u) = y_1.$$

Then it is easy to see that  $\pi$  is balanced for  $\phi$ .

## 7.2 Nonlinearity

Define a distance between two Boolean functions  $f_1$  and  $f_2$  by

$$d(f_1, f_2) = |\{X \mid f_1(X) \neq f_2(X)\}|.$$

The nonlinearity of a Boolean function  $f$ , denoted by  $N(f)$ , is defined by a distance between  $f$  and the set of affine functions.

$$N(f) = \min_{A(x)} |\{X \mid f(X) \neq A(X)\}|,$$

where

$$A(X) = a_0 + a_1x_1 + \dots + a_nx_n$$

is an affine function.  $N(f)$  must be large to avoid linear attack.

In this subsection, we show that our  $f$  has large nonlinearity if  $\pi$  is chosen appropriately in eq.(8). For  $f : \{0, 1\}^n \rightarrow \{0, 1\}$ , it holds that [15, 12]

$$N(f) \leq 2^{n-1} - 2^{(n/2)-1}.$$

If the equality is satisfied, then  $f$  is called a bent function. There exists a bent function if and only if  $n = \text{even}$  [15, 12].

**Theorem 7.2** *In Corollary 5.2, let  $s = n_1$  and  $u = n'_2$ . Then the  $\tilde{\delta}$ -almost PC( $\ell$ ) of order  $k$  function  $f : \{0, 1\}^n \rightarrow \{0, 1\}$  has nonlinearity such that*

$$\begin{aligned} N(f) &\geq 2^{n-m-1} - 2^{s+(u/2)-m-1} \text{ if } u = \text{even} \\ N(f) &\geq 2^{n-m-1} - 2^{s+(u-1)/2-m} \text{ if } u = \text{odd}, \end{aligned}$$

where  $n = s + u$  and  $m$  is given in Corollary 5.2.

(Proof) Remember that  $f$  is expressed by eq.(8).

If  $u = \text{even}$ , let  $\pi : \{0, 1\}^u \rightarrow \{0, 1\}$  be a bent function. We compute the distance between this  $f(X, Y)$  and an affine function  $A(X, Y)$  as follows. For  $\beta \in \{0, 1\}^s$ , define

$$\begin{aligned} f_\beta(Y) &= f(\beta, Y) = \phi(Y) \cdot G_1\beta + \pi(Y), \\ A_\beta(Y) &= A(\beta, Y) \end{aligned}$$

Then

$$\begin{aligned} d(f, A) &= \sum_{\beta \in \{0, 1\}^s} d(f_\beta, A_\beta) \\ &= \sum_{\beta \in \{0, 1\}^s} d(\phi(Y) \cdot G_1\beta + \pi(Y), A_\beta(Y)) \\ &= \sum_{\beta: G_1\beta = (0, \dots, 0)^T} d(\pi(Y), A_\beta(Y)) + \sum_{\beta: G_1\beta \neq (0, \dots, 0)^T} d(\phi(Y) \cdot G_1\beta + \pi(Y), A_\beta(Y)) \\ &\geq \sum_{\beta: G_1\beta = (0, \dots, 0)^T} d(\pi(Y), A_\beta(Y)) \\ &\geq 2^{s-m}(2^{u-1} - 2^{u/2-1}) \end{aligned}$$

because  $A_\beta(Y)$  is an affine function and  $\pi$  is a bent function, where  $N(\pi) = 2^{u-1} - 2^{u/2-1}$ . Therefore,

$$N(f) = \min_A d(f, A) \geq 2^{s-m}(2^{u-1} - 2^{u/2-1}) = 2^{n-m-1} - 2^{s+(u/2)-m-1}$$

because  $n = s + u$ .

If  $u = \text{odd}$ , let  $\pi' : \{0, 1\}^{u-1} \rightarrow \{0, 1\}$  be a bent function and define  $\pi(y_1, \dots, y_u) = \pi'(y_1, \dots, y_{u-1})$ . Then we obtain that

$$N(f) \geq 2^{s-m+1}(2^{t-2} - 2^{(u-1)/2-1}) = 2^{n-m-1} - 2^{s+(u-1)/2-m}$$

because  $N(\pi') = 2^{u-2} - 2^{(u-1)/2-1}$ .

Q.E.D.

**Remark 7.1** For  $\varphi : \{0, 1\}^u \rightarrow \{0, 1\}^s$  and  $\pi : \{0, 1\}^u \rightarrow \{0, 1\}$ , define

$$f(X, Y) = \varphi(Y) \cdot X + \pi(Y),$$

where  $X = (x_1, \dots, x_s)$  and  $Y = (y_1, \dots, y_u)$ . Then  $f : \{0, 1\}^{s+u} \rightarrow \{0, 1\}$  is a  $(s + u, 1, k)$ -resilient function for any  $\pi$  if the Hamming weight of  $\varphi(a)$

is strictly greater than  $k$  for any  $a \in \{0, 1\}^u$  [5, Sec.2.1]. Carlet studied the nonlinearity of this type of resilient functions [5].

Eq.(8) can be expressed like the above equation by letting  $\varphi(Y) = \phi(Y)G$ . However, we cannot apply the result of Carlet [5] because it is possible that  $\phi(a) = (0, \dots, 0)$  for some  $a \in \{0, 1\}^u$  in eq.(8).

## 8 Generalization to Multiple Output Bits

In this section, we generalize our result to multiple output Boolean functions.

**Definition 8.1** *We say that  $F(X) = (f_1, \dots, f_m)$  satisfies  $\varepsilon$ -almost PC( $\ell$ ) of order  $k$  if  $a_1 f_1 + \dots + a_m f_m$  satisfies  $\varepsilon$ -almost PC( $\ell$ ) of order  $k$  for any  $(a_1, \dots, a_m) \neq (0, \dots, 0)$ .*

**Theorem 8.1** *Suppose that there exist*

1. *a linear  $[n_1, m, k + 1]$ -code  $C_1$  with the dual minimum Hamming distance at least  $\ell + 1$  and*
2. *a linear  $[n_2, m - (D' - 1)t, k + 1]$ -code  $C_2$  with the dual minimum Hamming distance at least  $\ell + 1$*

*Then there exists a  $\delta$ -almost PC( $\ell$ ) of order  $k$  function  $F : \{0, 1\}^n \rightarrow \{0, 1\}^m$  such that  $n = n_1 + n_2$ , where*

$$\delta = \left(1 - \frac{1}{2^k}\right) \frac{2(D' - 1)}{2^{(t/2)+1-k}}.$$

(Proof) Let  $G_1$  be a generator matrix of a linear  $[n_1, m, k + 1]$ -code  $C_1$  with the dual minimum Hamming distance at least  $\ell + 1$ . Let  $\phi(Y)$  be an  $\varepsilon$ -almost  $(n_2, m, k)$ -resilient function with the domain distance  $d_\phi \geq \ell + 1$ .

Consider a linear feedback shift register of length  $m$  and with a primitive feedback polynomial. Let  $S$  be the state transition matrix of such a shift register. Let  $X = (x_1, \dots, x_{n_1})$  and  $Y = (y_1, \dots, y_{n_2})$ . For  $i = 1, \dots, m$ , define

$$f_i(X, Y) \triangleq \phi(Y) \cdot S^{i-1} G_1 X + g_i(Y)$$

where  $g_i(Y)$  is any Boolean function. Then we show that  $F(X, Y) = (f_1, \dots, f_m)$  satisfies  $(2^{m-1}\varepsilon)$ -almost PC( $\ell$ ) of order  $k$ .

For  $(a_1, \dots, a_m) \neq (0, \dots, 0)$ , we have

$$\begin{aligned} a_1 f_1 + \dots + a_m f_m &= \phi(Y) \cdot (a_1 I + a_2 S + \dots + a_m S^{m-1}) G_1 X \\ &\quad + a_1 g_1(Y) + \dots + a_m g_m(Y). \end{aligned}$$

It is easy to see that  $a_1 I + a_2 S + \dots + a_m S^{m-1}$  is a permutation of the space  $\{0, 1\}^m$ , as pointed out by Nyberg [14]. Therefore, this matrix is nonsingular. It implies that  $(a_1 I + a_2 D + \dots + a_m D^{m-1}) G_1$  is a generator matrix of the linear code  $C_1$ . Then from the proof of Theorem 4.1, we see that  $a_1 f_1 + \dots + a_m f_m$  satisfies  $(2^{m-1} \varepsilon)$ -almost  $PC(\ell)$  of order  $k$ .

The rest of the proof is straightforward from Sec.5.

Q.E.D.

## 9 On $t$ -systematic almost $k$ -wise independent sample space

In this section, we discuss on the previous construction of  $t$ -systematic almost  $k$ -wise independent sample spaces [9].

### 9.1 Previous Construction

Kurosawa, Johansson and Stinson showed a construction of  $t$ -systematic  $(\varepsilon, k)$ -independent sample spaces  $S_N$  [9] as follows.

**Definition 9.1** A polynomial  $h(x) \in GF(2^t)[x]$  is called a  $(2^t, D)$ -polynomial if  $h$  has degree at most  $D$  and  $a_i = 0$  for all even  $i$ , where  $h = \sum_{i=0}^D a_i x^i$ . Define  $Poly(2^t, D, k)$  to be a set of  $(2^t, D)$ -polynomials such that any  $k$  polynomials in the set are independent over  $GF(2)$ .

**Proposition 9.1** Suppose that  $g$  is a primitive element of  $GF(2^t)$ , and  $Poly(2^t, D, k)$  is chosen such that

$$\{x, gx, g^2x, \dots, g^{t-1}x\} \subseteq Poly(2^t, D, k).$$

Then there exists a  $t$ -systematic  $(\varepsilon, k)$ -independent sample space  $S_N$  where  $N = |Poly(2^t, D, k)|$  and  $\varepsilon = (D - 1)/\sqrt{2^t}$ .

(Proof sketch) Let  $Poly(2^t, D, k) = \{h_1, \dots, h_N\}$ . Construct a sample space  $S_N$  as follows: A binary string

$$\widetilde{X}_i = b_1 b_2 \dots b_N \in S_N$$

is specified by

$$b_j = \text{Tr}(h_j(x_i)),$$

where  $GF(2^t) = \{x_1, \dots, x_{2^t}\}$ . Let

$$S_N = \begin{pmatrix} \widetilde{X}_1 \\ \vdots \\ \widetilde{X}_2^t \end{pmatrix}$$

Then  $S_N$  is a  $t$ -systematic  $(\epsilon, k)$ -independent sample space with  $\epsilon = (D - 1)/\sqrt{2^t}$ .

Q.E.D.

The above  $\text{Poly}(2^t, D, k)$  can be constructed as follows. For a fixed (odd) degree  $D$ , we can express each polynomial as a linear combination of

$$x, gx, \dots, g^{t-1}x, x^3, gx^3, \dots, g^{t-1}x^3, \dots, x^D, gx^D, \dots, g^{t-1}x^D.$$

The polynomials in this set are clearly independent over  $GF(2)$ . Indexing the polynomials in  $\text{Poly}(2^t, D, k)$  as  $h_1, h_2, \dots, h_N$  we obtain a binary  $tD' \times N$  matrix, where  $D' = (D + 1)/2$ ,

$$H = \begin{pmatrix} h_{1,1} & h_{1,2} & \dots & h_{1,N} \\ h_{2,1} & h_{2,2} & \dots & h_{2,N} \\ \vdots & \ddots & \ddots & \vdots \\ h_{tD',1} & h_{tD',2} & \dots & h_{tD',N} \end{pmatrix},$$

where  $h_i(x) = h_{1,i}x + h_{2,i}gx + \dots + h_{tD',i}g^{t-1}x^D$ . Any  $k$  polynomials are independent over  $GF(2)$  means that any  $k$  columns of the above matrix are linearly independent. Hence the matrix corresponds to a parity check matrix of an  $[N, l, d]$  error correcting code, a code of length  $N = |\text{Poly}(2^t, D, k)|$ , dimension  $N - l = tD'$  and minimum Hamming distance  $d = k + 1$  [11].

In order to get a  $t$ -systematic sample space, we have already chosen the polynomials  $h_1 = x, h_2 = gx, \dots, h_t = g^{t-1}x$ . But clearly, this is no restriction, since any parity check matrix can be rewritten into such a form without changing the code parameters.

## 9.2 Relationship

We show that their  $S_N$  coincides with our  $S_N$  if we ignore the condition on the domain distance. Let

$$B(x) = (x, gx, \dots, g^{t-1}x, x^3, gx^3, \dots, g^{t-1}x^3, \dots, x^D, gx^D, \dots, g^{t-1}x^D).$$

Then

$$(h_1(x), \dots, h_N(x)) = B(x)H. \quad (11)$$

From eq.(11), it is easy to see that

$$\widetilde{X}_i = \text{Tr}(h_1(x_i)) \cdots \text{Tr}(h_N(x_i)) = \text{Tr}(B(x_i))H,$$

where

$$\text{Tr}(B(x_i)) = (\text{Tr}(x_i), \text{Tr}(gx_i), \dots, \text{Tr}(g^{t-1}x_i^D)).$$

Therefore, by letting

$$S_n = \begin{pmatrix} \text{Tr}(B(x_1)) \\ \vdots \\ \text{Tr}(B(x_{2^t})) \end{pmatrix}, \quad (12)$$

we obtain that

$$S_N = S_n H. \quad (13)$$

Here eq.(13) is the same as eq.(2), and eq.(12) is equivalent to eq.(6). Therefore, we can see that the previous construction coincides with our construction if we ignore the condition on the domain distance.

### 9.3 On the Domain Distance

However, it is essential that  $S_N$  has the domain distance at least  $\ell + 1$  in the construction of  $\varepsilon$ -almost  $PC(\ell)$  of order  $k$  functions. In the previous method [9],  $S_N$  is constructed directly from  $\text{Poly}(2^t, D, k)$ . From that point of view, we have no idea on how to impose the domain distance condition on  $S_N$ .

On the other hand, our  $S_N$  is constructed from the equation  $S_N = S_n H$ . From this point of view, it is very easy to impose the condition on the domain distance through  $H$ . Indeed, it is enough that  $H$  is a parity check matrix of a linear code with the dual minimum Hamming distance at least  $\ell + 1$ .

In [9], it was not shown that the  $S_n$  is an  $\varepsilon$ -biased sample space, neither.

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